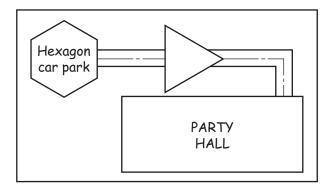
## Section A

Answer **all** questions in this section.

**A1** A sketch of a direction map from the Hexagon car park to the PARTY HALL is shown below.

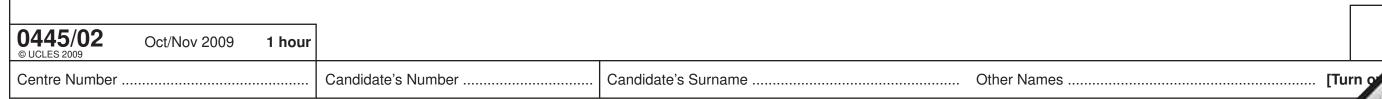


Complete the full-size plan view of the map by drawing in the space provided:

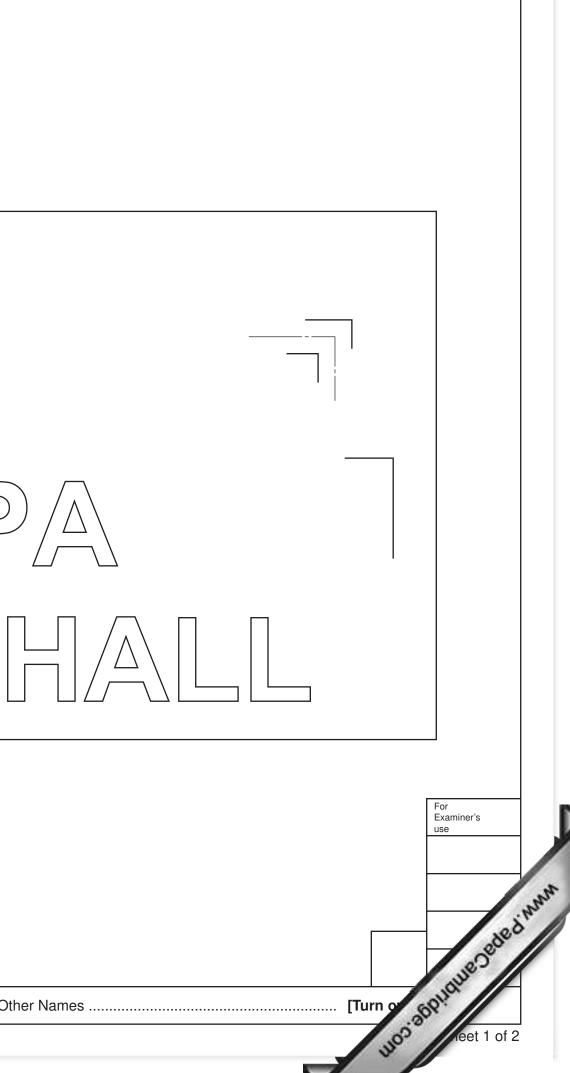
- a regular hexagon 30 side;
- an equilateral triangle 50 side; •
- the remaining pathway; •
- the outline of the PARTY HALL  $130 \times 70$ . [9] •

2 Complete the sign PARTY HALL by adding the three remaining letters.

All the letters must be the same height and style as those shown. [6]







- 100 -R150 50 50 200 600 \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ 200 500 scale 1:10 fence post 0445/02 © UCLES 2009 Oct/Nov 2009 1 hour
- **A3** A fence post is drawn to a scale of 1:10 in the orthographic views given to the left.

In the space indicated to the right:

- (a) draw an isometric view of the fence post. The drawing should be to the same scale and all sizes should be taken from the orthographic views; [7]
- (b) apply the thick and thin line technique to enhance your isometric drawing. [3]

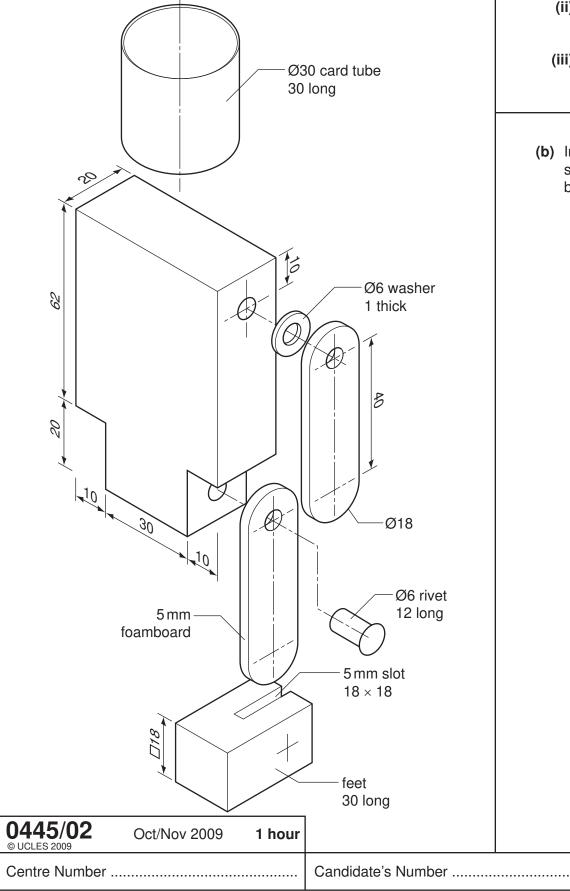
Isometric drawing

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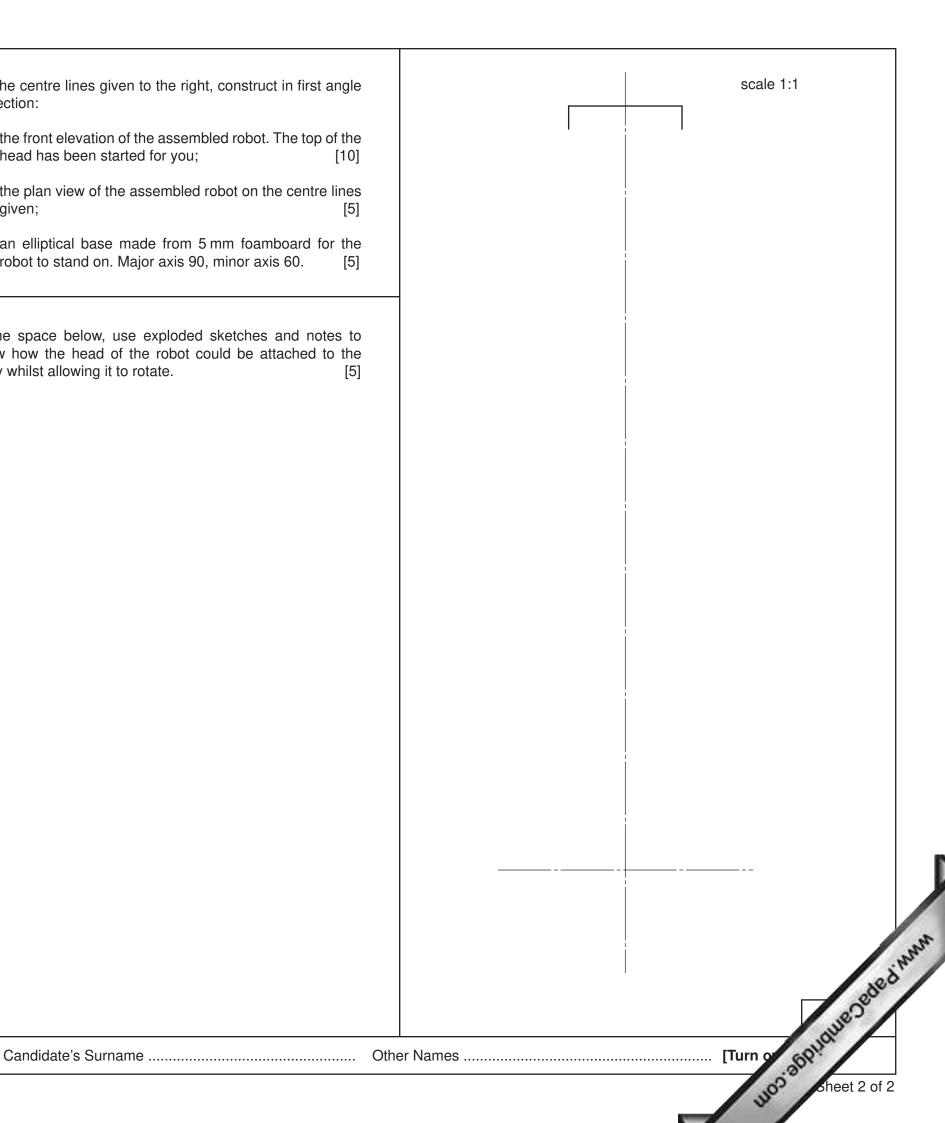
## Section B

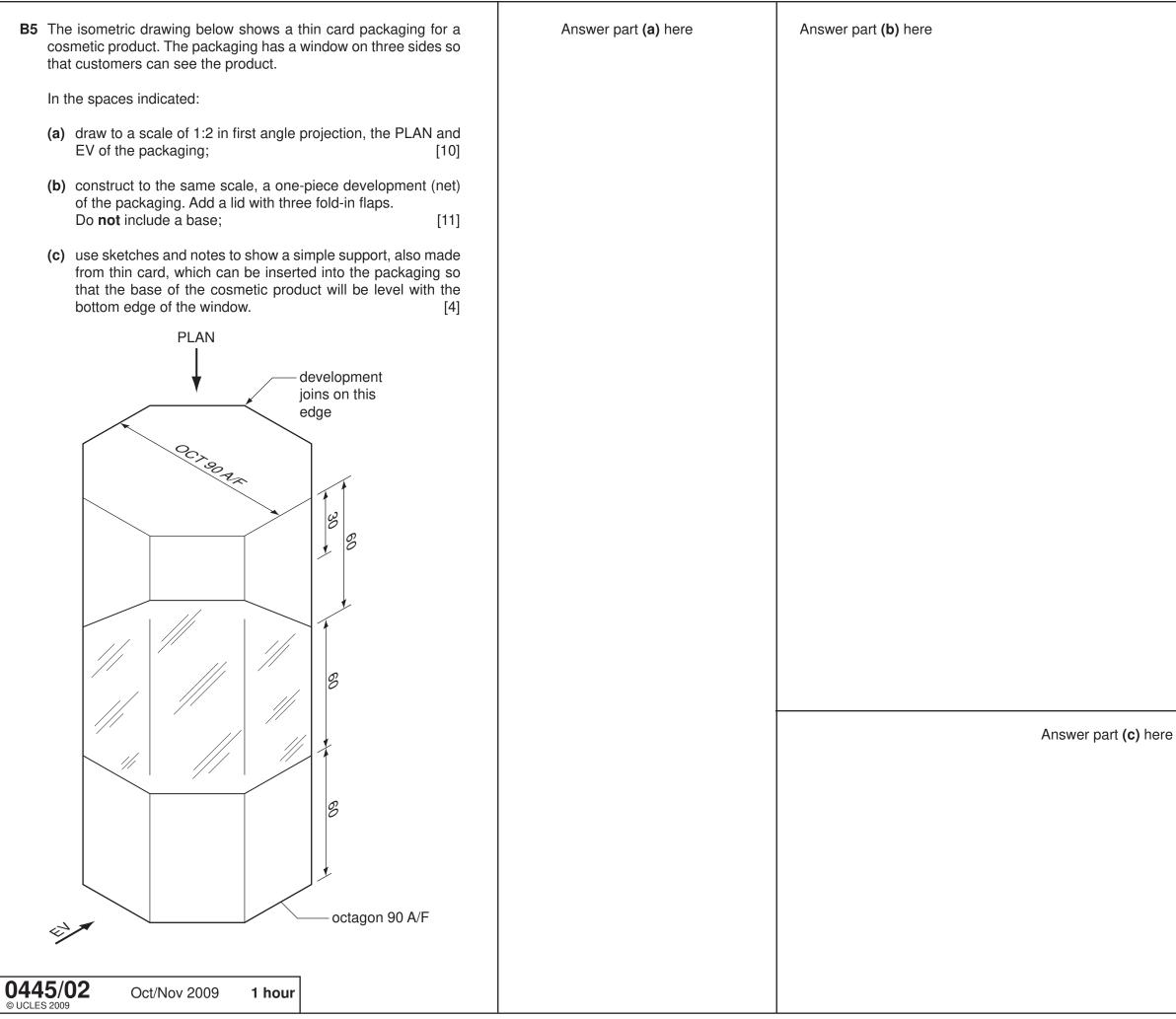
## Answer either question B4 or B5.

B4 Parts of a self assembly robot model are shown below. The parts are made from expanded polystyrene, card tube and foamboard. Ø6 plastic rivets join the arms, legs and feet together. Washers allow the arms and legs to move freely. Arms and legs are to the same dimensions.



- (a) On the centre lines given to the right, construct in first angle projection:
  - (i) the front elevation of the assembled robot. The top of the head has been started for you; [10]
  - (ii) the plan view of the assembled robot on the centre lines given; [5]
  - (iii) an elliptical base made from 5 mm foamboard for the robot to stand on. Major axis 90, minor axis 60. [5]
- (b) In the space below, use exploded sketches and notes to show how the head of the robot could be attached to the body whilst allowing it to rotate. [5]





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