UNIVERSITY OF CAMBRIDGE INTERNATIONAL EXAMINATIONS International General Certificate of Secondary Education

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for the guidance of teachers

0445 DESIGN AND TECHNOLOGY

0445/42 Paper 4 (Systems and Control), maximum raw mark 50

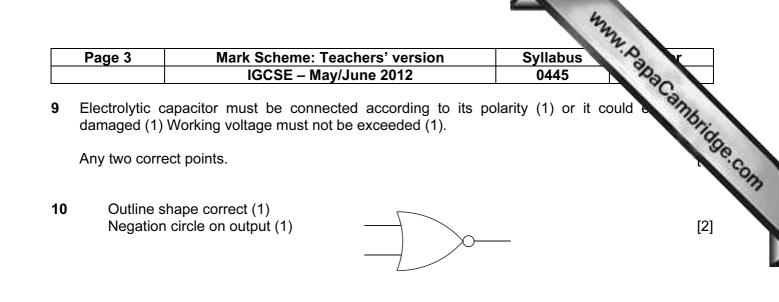
This mark scheme is published as an aid to teachers and candidates, to indicate the requirements of the examination. It shows the basis on which Examiners were instructed to award marks. It does not indicate the details of the discussions that took place at an Examiners' meeting before marking began, which would have considered the acceptability of alternative answers.

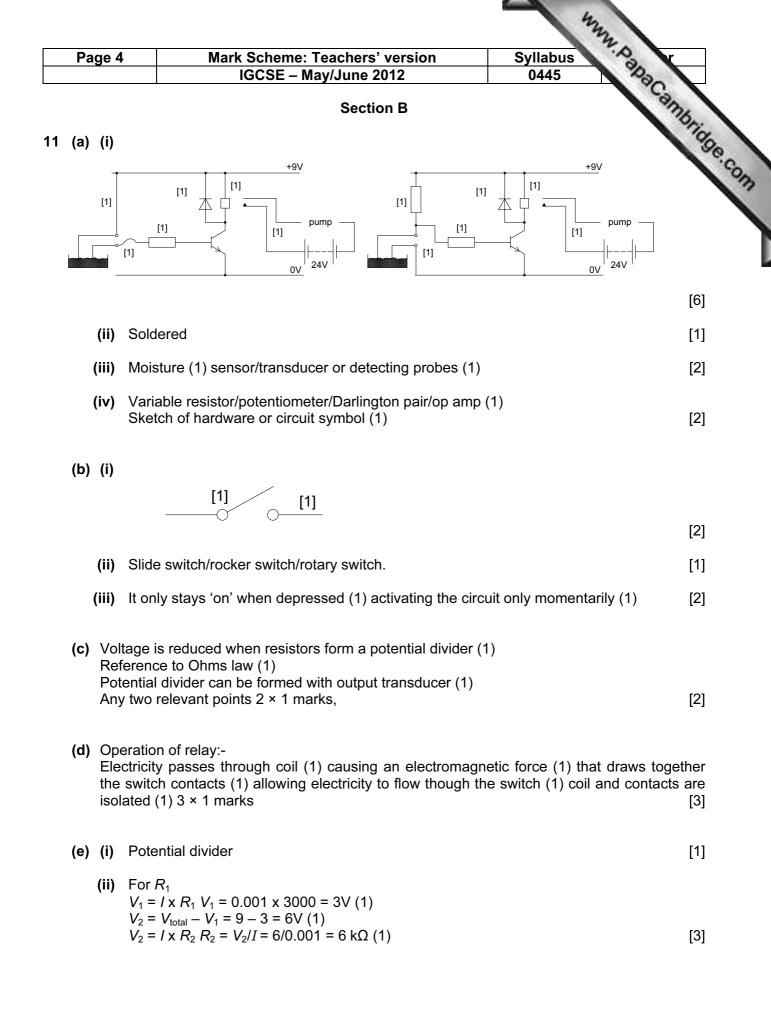
Mark schemes must be read in conjunction with the question papers and the report on the examination.

Cambridge will not enter into discussions or correspondence in connection with these mark schemes.

Cambridge is publishing the mark schemes for the May/June 2012 question papers for most IGCSE, GCE Advanced Level and Advanced Subsidiary Level syllabuses and some Ordinary Level syllabuses.

| Page 2 | Mark Scheme: Teachers' version IGCSE – May/June 2012 | Syllabus 0445 |
|--|--|--|
| | Section A | Canne |
| | hed door would sag/drop (1) so that it would change oor would not open/close properly (1) | Syllabus 0445 shape to a parallelogram (1) |
| | agonal braces correctly orientated nal(s) unsuitable position (1) | : |
| Gusset pla | ate | [1] |
| It will retur Extension | ial is behaving elastically (1) n to its original shape when loading is removed (1) proportional to load (1) Reference to Hookes Law (1) | |
| • | prrect points 2 × 1 marks. | [2] |
| (a) Worm | is input; wormwheel is output | [1] |
| (b) 32:1 | | [1] |
| | different sized spur gears (2) same size (1) g rotary motion to reciprocating motion (1) | [3] |
| Therefore | orium ACW Moments = CW moments 1 m x 800 N = X × 200 N (1) Nm /200 N = X (1) | |
| X = 4 m (1) | | [3] |
| First figure Second fig Multiplier o | gure 5 (1) of 100 (1) | |
| 7500 (Ω) c Allow 7.5 ł | | [3] |
| | | |





| (ii) Labelled appropriately (1) x 3 load – fulcrum - effort (iii) By lengthening the arm (1) from pivot to ball holder (1) Reduce distance (1) from load to fulcrum (1) 2 x 1 marks. Allow raising fulcrum height, wrapping rubber band around twice using stronger band. [2 (b) (i) For equilibrium RR = RL 1000 mm x E = 200 mm x 400 N (1) 200 x 400 N/1000 mm = E (1) E = 80 N (1) (ii) The force acting in pin B is Shear (c) (i) Rotational/Rotary Oscillation (either way around) (ii) P Pear (1) Cam (1) Q Lever (1) Follower(1) (iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) (e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | Pa | ge 5 | Mark Scheme: Teachers' version | Syllabus Syllabus |
|---|-------|-------|---|---|
| (b) (i) For equilibrium RR = RL 1000 mm x E = 200 mm x 400 N (1) 200 x 400 N/1000 mm = E (1) E = 80 N (1) (ii) The force acting in pin B is Shear (c) (i) Rotational/Rotary Oscillation (either way around) (ii) P Pear (1) Cam (1) Q Lever (1) Follower(1) (iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) (a) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | | | IGCSE – May/June 2012 | 0445 73 |
| (b) (i) For equilibrium RR = RL 1000 mm x E = 200 mm x 400 N (1) 200 x 400 N/1000 mm = E (1) E = 80 N (1) (ii) The force acting in pin B is Shear (c) (i) Rotational/Rotary Oscillation (either way around) (ii) P Pear (1) Cam (1) Q Lever (1) Follower(1) (iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) (a) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | 2 (a) | (i) | First class/first order. | ambr |
| (b) (i) For equilibrium RR = RL 1000 mm x E = 200 mm x 400 N (1) 200 x 400 N/1000 mm = E (1) E = 80 N (1) (ii) The force acting in pin B is Shear (c) (i) Rotational/Rotary Oscillation (either way around) (ii) P Pear (1) Cam (1) Q Lever (1) Follower(1) (iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) (a) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | | (ii) | Labelled appropriately (1) x 3 load – fulcrum - effort | |
| 1000 mm x E = 200 mm x 400 N (1) 200 x 400 N/1000 mm = E (1) E = 80 N (1)[3](ii) The force acting in pin B is Shear[7](c) (i) Rotational/Rotary Oscillation (either way around)[7](ii) P Pear (1) Cam (1) Q Lever (1) Follower(1)[2](iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks[4](d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable.[7](ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1)[3](e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | (| | Reduce distance (1) from load to fulcrum (1) 2 x 1 marks | s. nd twice using stronger band. [2] |
| (ii) The force acting in pin B is Shear (c) (i) Rotational/Rotary Oscillation (either way around) (ii) P Pear (1) Cam (1) Q Lever (1) Follower(1) (iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) (e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | (b) | () | 1000 mm x E = 200 mm x 400 N (1) 200 x 400 N/1000 mm = E (1) | [3] |
| (c) (i) Rotational/Rotary Oscillation (either way around) (ii) P Pear (1) Cam (1) Q Lever (1) Follower(1) (iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) (e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | | | | - |
| Oscillation (either way around)[1](ii) P Pear (1) Cam (1)[2]Q Lever (1) Follower(1)[2](iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks[2](d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable.[1](ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1)[2](e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | | (11) | The force acting in pin B is Shear | [1] |
| (ii) P Pear (1) Cam (1) [2 Q Lever (1) Follower(1) [2 (iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks [2 (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. [7 (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) [3 (e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | (c) | (i) | • | [1] |
| Q Lever (1) Follower(1) [2 (iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks [2 (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. [7 (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) [3 (e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | | (::) | | |
| (iii) Two appropriate examples: Intermittent switching; moving parts on toys 2 x 1 marks (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) (e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | | (11) | P Pear (1) Cam (1) | [2] |
| Intermittent switching; moving parts on toys 2 x 1 marks (d) (i) Steering of vehicles, adjustment on pillar drill table or other suitable. (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) (e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | | | Q Lever (1) Follower(1) | [2 |
| (ii) Ratio = 1 : 10 (1) 1m/10 (1) = 100 mm (1) (e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | (| (iii) | | [2 |
| 1m/10 (1) = 100 mm (1) [3 (e) (i) Movement is smoother (1) so less effort needed (1) Friction is reduced (1) easier to move (1) efficiency is increased (1). | (d) | (i) | Steering of vehicles, adjustment on pillar drill table or oth | ner suitable. [1] |
| Friction is reduced (1) easier to move (1) efficiency is increased (1). | | (ii) | | [3] |
| · · · · · · | (e) | | Friction is reduced (1) easier to move (1) efficiency is inc | creased (1). [2 |
| (ii) Oil or grease. | | | | [1] |
| | | | | |

| | | | | | | | | | | | | | Ĵ | | m | | | bilds. | |
|--------|-----|-------|--|---|-----------|-----------------------------|--------------------|---------|---------|--------|---------------------|----------|-------------|---------|-------|--------|--------|------------|-----|
| Page 6 | | | | Mark Scheme: Teachers' version Syllabus | | | | | | | | | Q. | V | | | | | |
| | | • | | | | IGC | SE – | May/ | /June | 2012 | | | (|)445 | | 10 | 2 | | |
| 13 | (a) | (i) | Shad | ackle: | Tens | ion | | | | | | | | | | | Can | 16ri | |
| | | | Bolt: Double (1) Shear (1) | | | | | | | | | | | 3 | | | | | |
| | | (ii) | Elas | sticity | | | | | | | | | | | | | | [1] | COM |
| | (b) | | e curve of the shackle (1) allows stress to flow round the shackle (1) this stops st ncentration points (1) that cause failure. | | | | | | | | | | ress [3] | | | | | | |
| | (c) | (i) | Enables a rope/cable to be passed through the shackle (1) easily and quickly (1). | | | | | | | | | | | [2] | | | | | |
| | | (ii) | Nam Exar | | | • | ember | rs in a | n frame | ework | for a tra | ailer ch | assis | i | | | | [1] [1] | |
| | (d) | Bra | ace or triangulation (1) for increasing rigidity/stability (1) | | | | | | | | | [2] | | | | | | | |
| | (e) | | | | | | | • | • | • • | so that propriat | | | | d the | integr | ity of | the [3] | |
| | (f) | (i) | 250 | N/m | $m^2 = 0$ | ressive C/4 mn : 1000 | n ² (1) | | s-sect | tional | area (1) |) | | | | | | [3] | |
| | | (ii) | | | | | | | | | le due t applied | | xterna | al forc | e (1) | | | [3] | |
| | | (iii) | 0.06 | 3/30 (| | | 30-29.9 | .94 = (| 0.06 m | nm (1) | | | | | | | | [3] | |