MARK SCHEME
Maximum Mark: 50

## Published

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Mark schemes should be read in conjunction with the question paper and the Principal Examiner Report for Teachers.

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| Question | Answer |  |  |  | Marks | Guidance |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1(a) |  | Type | Action | Contact arrangement | 3 |  |
|  | Switch A | toggle switch | on / off | SPDT |  |  |
|  | Switch B | push switch | PTB | SPST |  |  |
|  | Switch C | push switch | PTM | SPST |  |  |
|  | 1 mark for each correct. |  |  |  |  |  |
| 1(b) | Circle should be around 6. |  |  |  | 1 |  |


| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 2 | LED Anode to +6 V , 1 mark <br> Ammeter connected in series (could be above LED or below resistor), 1 mark Resistor connected to 0V, 1 mark. | 3 | Other combinations of connection are possible but LED anode has to be connected to +6 V either directly or below ammeter. |


| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 3 | Advantages of transistor switch could be: <br> - Fast switching <br> - No contact bounce / no moving parts <br> - Low cost <br> - Not manually operated <br> - Low failure rate <br> - Smaller than a mechanical switch <br> 1 mark for each valid advantage | 2 | Allow other valid advantages. E.g. low current used to switch a higher current. |


| Question | Answer | Marks |
| :---: | :--- | :---: |
| 4(a) | Oscillating to Oscillating movement, 1 mark for each term. | $\mathbf{2}$ |
| $4(\mathrm{~b})$ | Second order or class 2 lever. | $\mathbf{1}$ |
| $4(\mathrm{c})$ | The gear [1] transmits motion by meshing with the holes in lever [1] | $\mathbf{2}$ |


| Question | Answer | Marks | Guidance |
| :---: | :--- | :---: | :---: |
| 5 | Any suitable third order lever, e.g. tweezers [1]. <br> Position of effort shown between load and fulcrum, <br> 1 mark each for L E F correctly positioned, 3 $\times 1$ mark | 4 |  |


| Question | Answer | Marks | Guidance |
| :---: | :--- | :---: | :---: |
| 6 | Any natural frame structure, 1 mark | $\mathbf{1}$ | No marks for man- <br> made structures |


| Question | Answer | Marks | Guidance |
| :---: | :--- | :---: | :---: |
| 7 | Any natural shell structure, 1 mark | $\mathbf{1}$ | No marks for man- <br> made structures |


| Question | Answer | Marks | Guidance |
| :---: | :--- | :---: | :---: |
| 8 | Gusset, brace or tie used 1 mark. <br> Correct position, e.g. tie used above joint, brace below joint, gusset either above or below joint, 1 mark. <br> Clear sketches / notes to show fixing method / how the reinforcement would work, 1 mark. | 3 |  |


| Question | Answer | Marks | Guidance |
| :---: | :--- | :---: | :---: |
| 9 | Description could relate to: <br> $\bullet$ clockwise moment = anticlockwise moment, opposing forces being equal or a state of balance, 1 <br> mark <br> Stability or no movement, 1 mark | $\mathbf{2}$ |  |


| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 10(a) | Part .......A........ is a strut, which is placed there to resist compression <br> Part ......B........ is a tie which will resist tension <br> When the roof covering is added part $\mathbf{C}$ will have to resist a bending force. | 5 | 1 mark for each term correctly placed |
| 10(b)(i) | Elastic deformation allows the material to go back to its original shape / length [1] after the loading is removed [1] | 2 | Allow 1 mark for some understanding shown. |
| 10(b)(ii) | Elastic limit is the maximum that a material can be stretched [1] without any permanent change to its shape / length [1]. | 2 | Allow 1 mark for some understanding shown. |


| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 10(b)(iii) | Plastic deformation is permanent deformation of the material [1] without any fracture occurring [1]. | 2 | Allow 1 mark for some understanding shown. |
| 10(c)(i) | 3 / three cables is the minimum, 1 mark. | 1 |  |
| 10(c)(ii) | Functional method [1] Adjustment possible [1] Clear understandable sketch / notes [1]. | 3 |  |
| 10(c)(iii) | Shear force, 1 mark. | 1 |  |
| 10(c)(iv) | $\begin{aligned} (0.9 \times \mathbf{X})+(0.45 \times 25) & =2.55 \times 125,1 \text { mark } \\ 0.9 \mathbf{X}+11.25 & =318.75,1 \text { mark } \\ \mathbf{X} & =(318.75-11.25) / 0.9,1 \text { mark } \\ \mathbf{X} & =\mathbf{3 4 1 . 6 6 \mathbf { N } , 1 \text { mark }} \end{aligned}$ | 4 | Award 4 marks for correct answer with no working. |
| 10(d) | Static loads are those that do not change [1] made up of construction materials used in the building of the bridge [1] <br> Dynamic loads are changing values [1] made up of vehicles, pedestrians, animals or the loading caused by changing weather conditions. [1] | 4 | For changing weather conditions allow: <br> High winds, snow, heavy rain, earthquake. <br> For static loads allow any item described as stationary. |
| 10(e) | Reasons for using aluminium honeycomb could include: <br> - Low weight / high strength <br> - Resistance to twisting / torsion <br> - Moisture and corrosion resistance <br> - High thermal conductivity | 1 | Do not allow marks for 'strong' with no justification |


| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 11(a) | Power Source Safety Device | 3 | 1 mark for each correct. |
|  | mains electricity $\quad$ residual current device RCD |  |  |
|  | natural gas solenoid valve |  |  |
|  | low voltage electricity fuse |  |  |
|  | compressed air regulator |  |  |
| 11(b)(i) | The driven pulley will turn anti-clockwise, 1 mark, The speed of the driven pulley will be slower than the driver, 1 mark. | 2 |  |
| 11(b)(ii) | 1 mark for each arrow correct, $2 \times 1$ marks. | 2 | Arrows may be in different positions on the drawing. |
| 11(b)(iii) | Benefits of a belt drive could include: <br> - Pulley position is not so critical <br> - Belt can slip to save damage if a shaft is jammed <br> - Lower initial cost and replacement belt cost than gears <br> - Can be quieter in operation than gears <br> - No lubrication required. <br> $2 \times 1$ marks for valid benefits | 2 | Allow other valid benefits |


| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 11(b)(iv) | Explanation should include: <br> - Frictional losses <br> - Energy lost in generation of heat and sound <br> - Poorly fitting parts <br> - Materials that cause losses e.g. belts that stretch or slip on initial start-up. <br> $3 \times 1$ marks for each point in explanation. | 3 | Clear explanation with at least two points included, one point being well explained[3] Explanation with up to three points mentioned but no links to consequence of the cause of energy loss , [2] Award two marks for one point well explained. <br> Single point mentioned, [1] |
| 11(c)(i) | Bevel gear, 1 mark | 1 |  |
| 11(c)(ii) | Reasons will include: <br> - It can change the direction of the drive through $90^{\circ}$ <br> - Positive drive with no chance of slipping <br> - Suited to large difference in 1 number of teeth on the two gears. <br> $2 \times 1$ marks. | 2 | Allow other valid reasons e.g. increased speed of driven gear. |
| 11(c)(iii) | 12:56 or 6:28 or 3:14 or 1:4.67 <br> Correct numbers 1 mark, correct way around, 1 mark. | 2 |  |
| 11(c)(iv) | $\begin{aligned} \text { Speed of chuck } & =(56 / 12) \times \mathbf{6 0}, 1 \text { mark } \\ & =280 \mathrm{rpm}, 1 \text { mark } \end{aligned}$ | 2 | 2 marks for correct answer with no working. |


| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 11(c)(v) | Problems with plain bearings include: <br> - Shorter working life than other types of bearing <br> - Replacement may not be possible <br> - Not as precise a fit in many cases <br> - Lubrication will be required; other types can be sealed for life. <br> - More friction / heat is generated <br> 1 mark for valid answer. | 1 |  |
| 11(c)(vi) | The ball bearing absorbs the thrust from the end of the shaft, [1] when the drill bit is pressed onto the work. [1] <br> Friction at the end of the shaft is reduced [1]. | 2 | Explanation with two points included [2] Explanation with a single point included [1] <br> Allow 2 marks for one point fully explained. |
| 11(d) | Mechanical advantage of the first lever is $800 / 75=\mathbf{1 0 . 6 6}$ Mechanical advantage of the second lever is $40 / 220=\mathbf{0 . 1 8}$ Combined advantage is $10.66 \times 0.18=1.94$ | 3 | 3 marks for correct answer with no working. |


| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 12(a)(i) | 1 mark for both voltmeter connections correct. <br> from power supply | 1 |  |
| 12(a)(ii) | Current calculation 1 mark for 9.5/60=0.16 A or $158 \mathrm{~mA}, 1$ mark | 2 |  |


| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 12(a)(iii) | $\begin{aligned} \text { Power calculation } P & =9.5 \times 0.158,1 \text { mark } \\ & =\mathbf{1 . 5} \mathbf{W}, 1 \text { mark. } \end{aligned}$ | 2 | Allow ecf on value of current |
| 12(b)(i) | Reasons for tinning will include: <br> - Prevent oxide formation on the copper track / pads <br> - Make soldering easier / solder adheres better to a tinned surface <br> - Better chance of a successful joint. <br> $2 \times 1$ marks | 2 |  |
| 12(b)(ii) | Stages could include: <br> - Putting notch next to pin 1 on board <br> - Aligning all pins with holes <br> - Checking that no pins are folded under the holder <br> - Bending pins on track side to keep IC holder in place <br> - Application of soldering iron to both pin and pad <br> $3 \times 1$ marks for valid stages | 3 |  |
| 12(b)(iii) | - Notes and sketches to show board inverted and supported under resistor [1] <br> - Joint heated with soldering iron[1] <br> - Pressure applied to push resistor down[1]. | 3 | Allow use of desoldering tool rather than soldering iron. |
| 12(c)(i) | Output of one gate to an input of the other, 1 mark input 1 <br> input 2 $\square$ [1] <br> input 3 | 1 | Other arrangements are possible but all must have an output connected to an input. |
| 12(c)(ii) | Labels correct for 3 inputs, 1 mark. | 1 |  |



| Question | Answer | Marks | Guidance |
| :---: | :---: | :---: | :---: |
| 12(d)(iii) | Explanation could include: <br> - Ease of changing delays <br> - Ease of changing sequence during development <br> - Higher number of usable inputs and outputs <br> - Sequence can easily be changed after manufacture <br> - Low cost of PIC compared to discrete components <br> - Circuit will be less complicated / fewer components <br> - Additional features can be built in. <br> $3 \times 1$ marks for each point used. Allow 2 marks for one point well explained. | 3 | Allow other valid points in explanation |

